

## Description

The PR 10 is a through-shaft potentiometric transducer which converts a rotary movement into a resistance change.

It is established by a precision potentiometer that, trough a timely transmission receives the control-shaft movement and signals the position to a display or to a position controller.



## Precautions during assembling

- Do not exceed the maximum allowable rpm.
- For electrical connections always use a shielded cable (with shield connected to GND) which must be kept separate from power lines or sources of electromagnetic interference.
- Make the electrical connections with due care and attention: a failure due to a connection error renders the guarantee null and void
- The power supply must fall within the admissible range, a value exceeding this range or an alternate current could damage the encoder.

## **Technical Characteristics**

٠	Gear	Straight toothed gear
٠	Normal form	1 mm
٠	Gear numbers	10
٠	Pressure angle	20°
٠	Diametral pitch	10 mm
٠	Outside diameter	12 mm
٠	Linearity	± 0,25%
٠	Resistance	10 KOhm
٠	Max. rotation speed with	300 RPM continuous, 500 RPM for short periods
	transmission ratio 1:1	
٠	Connector output K type 15x15 mn	n 4 poles DIN 43650
٠	Cableclamp	PG7, cable diameter 4 - 6 mm
٠	Technopolymer, blow-resistant, se	If-extinguishing housing resistant to solvents, petrol, oils, grease.
٠	Degree of protection	IP54
٠	Colour	RAL 7004 Grey
٠	Temperature of operation	-10 - 70°C
٠	Relative humidity	35 - 85%

Directive: 2014/30/EU Electromagnetic compatibility, 2011/65/EU RoHS